Public Information: Relevance or Salience? *

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Abstract

How does salient public information affect voters’ behavior? In a majoritarian voting game with common preferences, rational voters could use public information as an information device (depending on accuracy) or as a coordination device (regardless of accuracy). A simple lab experiment contradicts both hypotheses: subjects tend to follow public information when it is salient, regardless of the information’s accuracy, but fail to use it as a source of coordination. In particular, it matters whether the information is recent: subjects are more likely to follow public information when it is provided closer to the voting decision. These findings are important because the salience of public information is easily manipulable by political actors.

Keywords: Information Aggregation, Committee Decision Making, Voting Experiment, Recency Bias.

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Introduction

When voters have to decide over issues of common interest, they often find themselves influenced by visible events of debatable direct relevance. Before winning the Democratic nomination in 2008, Obama was endorsed by Oprah Winfrey in Iowa, and the endorsement was one of the most widely covered developments of the campaign: Garthwaite and Moore (2012) estimated that Oprah’s endorsement was responsible for approximately 1 million additional votes for Obama. During the 2016 EU referendum in England, Roger Daltrey (lead singer of the iconic rock band The Who) explained in an interview by The Mirror why he thought Brexit was the right thing to do.¹ Taylor Swift made perhaps the most high-profile celebrity intervention in the 2018 Midterm campaign when she shared on social media a photograph of herself and her mother waving American flags next to a billboard for Democratic Senate candidate Phil Bredesen. These examples share the attribute that the information provided is public but salient, particularly noticeable. In the case of the endorsement to Obama, voters might have seen it as an informative public signal, thinking that Oprah had precise information about the candidate, or as a coordination device, believing that everyone else observed it. Alternatively, they could have paid attention to the endorsement because it was extremely noticeable, as Oprah is a famous celebrity and the endorsement happened right before the election.

This paper uses a laboratory experiment to study how salient public information affects collective decision making. There are three main explanations for why salient public information could be influential. First, if the information provided is more accurate than voters’ private information, then voters may trust the public source more. Second, public information can serve as a coordination mechanism for voters,

¹As anecdotal evidence, Google searches for celebrities and Brexit peaked in the week before the referendum, and many web pages displayed long lists of Brexit’s supporters.
who may then rationally choose to disregard their private information and follow the public source even when the latter is not accurate. Finally, salient public information can be influential because of biases or heuristics affecting voters’ decision. This paper analyzes each of these explanations.

Salience of information affects how people focus their limited cognitive resources. Salience bias (or perceptual salience) refers to the fact that individuals focus more on information that is striking and perceptible and ignore information that is less so (Kahneman and Tversky, 1984, Taylor and Thompson, 1982). One attribute of salience that is particularly effective in politics is recency. According to the recency bias (or availability heuristic), people tend to heavily weight their judgments towards information received more recently, making new opinions biased toward latest news (Tversky and Kahneman, 1974, Crowder, 2014). Public information delivered close to the vote (as Oprah’s endorsement) can be overweighted by voters, who have it readily available in their short-term memory. In real-world situations it is hard to tell why voters respond to salient public information. In particular, it is difficult to separate the importance of the way information is framed from its content, as typically the two come together. This experiment is designed precisely to overcome this challenge.

I begin with the canonical majority rule committee setting, where voting aggregates members’ independent signals about the state of the world (Condorcet, 1785, Austen-Smith and Banks, 1996). When in addition a public signal is observed by all voters, they could use the public information as an information device (depending on accuracy) or as a coordination device (regardless of accuracy). If the public signal is more precise than each private signal, then majority rule no longer leads

\(^2\)For a discussion of how salience can affect individual decision making, see Bordalo et al. (2012).

\(^3\)This challenge is posed by Strömberg (2015), who suggests that to isolate framing mechanisms, one would need to study the effect of completely uninformative events.
to an equilibrium in which every voter always votes according to the private signal (Kawamura and Vlaseros, 2017). Moreover, for any relative accuracy of the two signals, a conformist equilibrium exists where no voter is pivotal and all coordinate on the basis of the public information.

To these two possible roles of the public signal - information and coordination - a laboratory experiment superimposes a third element: salience. Subjects face structurally equivalent games which differ in the salience of the information provided. One salience treatment is designed to explicitly capture subjects’ attention, by emphasizing the information with graphics and music. Another treatment changes the relative timing of private and public signals. If subjects behaved according to the equilibrium predictions, their behavior would not change substantially across different salience treatments. If, on the other hand, subjects were to process information according to salience bias, we would expect more votes for the public signal when this is salient.

The experimental results show that subjects’ behavior is responsive to signals’ precision: when the public signal is more accurate than the private, subjects follow it more than when it is less accurate than the private one. Yet, the behavior observed is far from the responsive equilibrium predictions. Subjects’ behavior also contradicts the coordination mechanism: although the conformist equilibrium is not responsive to signals’ relative precision, subjects’ behavior is. Results, instead, point towards the role of salience of information. In particular, the order of message delivery matters: subjects tend to follow the public signal more when it is the most recent signal observed before voting. Recency has a substantive and statistically significant impact on subjects’ behavior: in all the experimental sessions subjects follow the most recent signal (the last signal observed before voting) 75% of the time, regardless of the signal’s precision. Moreover, recency has a striking homogeneous
effect: the proportion of votes with the public signal under the recency treatment is greater than the proportion of votes with the public when this is displayed before the private one, for almost every subject in the experiment and regardless of signals’ relative accuracy. Interestingly, this result is robust to additional sessions where subjects do not vote in committees over issues of common interest, making individual choices instead. Finding the same behavior in the individual sessions suggests that coordination on information does not explain subjects’ behavior.

This paper relates to the literature studying salience bias in voters’ decisions. In particular, recency effects have been studied in the context of electoral campaigns. Gratton et al. (2016) analyze a sender-receiver game connecting the timing of information release with voter beliefs prior to elections. They formally derive an equilibrium in which fabricated scandals are only released close to the election date, and confirm their equilibrium prediction using data on the release of US presidential scandals. Timing of message delivery in electoral campaigns has also been the subject of field experiments. Nickerson (2007) studies the effect of phone calls by volunteers on voter turnout. He finds that calls made during the final days prior to the election are most effective in mobilizing voters, and that the specific content of the conversation is less important than the timing of the call. This paper’s contribution is to provide a controlled experimental test of the role of salience public information on voting. While in field experiments it is hard to isolate the importance of salience from the informational content a message provides, this experimental design overcomes this challenge.

The paper also relates to the literature on committee decision making in voting experiments. The specific paper that I most closely relate to is Kawamura and Vlaseros (2017). The authors focus on the information and coordination mechanisms with private and public signals and show with a laboratory experiment that
voters might be drawn to inefficient conformist equilibria where private information is ignored and voters conform to the public signal. Their design mainly focuses on the case of a public signal that is more precise than private ones. In one additional treatment they consider a less precise public signal, and another treatment presents the same public information in a less salient way (as a common asymmetric prior). Both these treatments lead subjects to vote less for the public signal. My experimental design is fundamentally different as it focuses on the role of salience: one treatment changes signals’ relative timing, another one emphasizes the public signal by making it shocking. Furthermore, in order to test for the coordination mechanism, one treatment presents the same task as a simple individual-decision making problem, where there is no pivotality calculation involved. By doing so, this paper contributes to the literature by showing what are the attributes of the public signal that lead subjects to follow it more than what prescribed by the equilibrium predictions derived by canonical committee decision making models.

The ability to detect what deserves attention is an important mechanism that allows people to focus on key information. However, when making important decisions such as voting, people may focus on features that are easy to process and vivid because available in short-term memory, rather than more informative but less salient ones. This bias in information processing can lead to suboptimal decisions. Knowing this, politicians and media can influence what voters judge to be salient by altering the time of issues coverage, and by doing so shift voters’ attention to events that take place at strategic times.

The remainder of the paper is organized as follows. The next section describes the theoretical model and equilibrium predictions. The following sections present experimental design and results. The last section concludes. Proofs, additional data and a copy of the experimental instructions are reported in the Appendix.
The Model

Consider a committee that consists of \(n\) members, where \(n\) is odd. Agents make a collective decision \(d \in D = \{A, B\}\) over two alternatives. The state of the world is \(\omega \in \Omega = \{A, B\}\). Both events are ex ante equally likely: \(Pr(A) = Pr(B) = \pi = 0.5\), where \(\pi\) is the common prior.

Each agent casts a vote for one of the two alternatives \(\{A, B\}\): we define the individual vote \(v_i = a\) if the agent votes in favor of alternative \(A\), and \(v_i = b\) otherwise. The agent’s action set is \(V_i = \{a, b\}\) and the agents’ voting profile is denoted by \(v = (v_1, v_2, v_3, ..., v_n)\).

The committee decides by majority voting. Committee members have identical preferences, and payoffs are normalized without loss of generality to 0 or 1. Specifically, I denote by \(u_i(d, \omega)\) the utility to voter \(i\) of decision \(d\) in state \(\omega\) and assume \(u_i(A, A) = u_i(B, B) = 1\) and \(u_i(A, B) = u_i(B, A) = 0\) for each member of the committee. This means each agent wants the collective decision to match the state of the world.

Agents receive two pieces of information before voting: a private and a public signal. The private signal is denoted by \(s_i \in S_i = \{\alpha, \beta\}\). The probability of the signal matching the state is symmetric across the two states and given by \(Pr[s_i = \alpha | A] = Pr[s_i = \beta | B] = q \in (\frac{1}{2}, 1)\). The public signal is denoted by \(s_p \in S_p = \{\alpha, \beta\}\), with \(Pr[s_p = \alpha | A] = Pr[s_p = \beta | B] = Q \in (\frac{1}{2}, 1)\). Private signals are conditionally independent across voters, and the public signal is conditionally independent from the private signals. We can think of the public signal as information contained in the news released by the media, such as The Mirror’s interview to Roger Daltrey. Alternatively, we can consider more sophisticated voters such as politicians in a congressional committee: the public signal could be a technical report presented

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4Assume there is no cost of casting votes.
during a meeting. An agent’s private signal is the private information that he holds independently of the other committee members, which can be superior to the technical report, depending on the quality of the last one. Notice that, without public signals, there exists an equilibrium where each voter follows his private signal and as the number of committee member grows, the probability that the majority takes the correct decision tends to one (Austen-Smith and Banks, 1996, Condorcet, 1785).

The timing of the game is as follows:

1. Nature determines the state of the world $\omega$.

2. Each voter observes a private signal and the same public signal (observed by everyone).

3. Agents cast their votes and the collective decision $d$ is determined according to the majority of votes.

4. The true state is revealed and agents receive their payoffs.

**Equilibrium Analysis**

I begin by restricting the analysis to responsive equilibria symmetric across voters and across states. Symmetry implies that all committee members who receive the same signal take the same (possibly mixed) action. Responsiveness means that voters change their vote as a function of their own signals with positive probability. An agent’s vote depends on the two signals she receives, and whether the public signal and the private signal agree ($s_i = s_p$) or disagree ($s_i \neq s_p$).

In this setting, a pure voting strategy is a function $v_i : S_i \times S_p \to V_i$ that maps the Cartesian product of the private and public signal space into the action space,
i.e. $v_i : \{\alpha, \beta\}^2 \rightarrow \{A, B\}$. Given that payoff functions are normalized to 0 and 1, the expected utility of alternative $A$ being chosen (given the observed signals) equals the probability that $A$ is the true state of the world, and the same is true for $B$. The next Lemma shows the conditions for having an equilibrium where the vote of every voter is responsive to the public (and private) signal.

**Lemma 1.** Suppose $Q \leq q$. Then there exists a unique informative equilibrium and in equilibrium each agent always votes with her private signal.

*Proof.* See Appendix for derivation.

To get the intuition for Lemma 1, consider the decision of a voter. Under the event of pivotality, half of the other voters vote for $A$ and half for $B$. The voter observes the public and private signals, which differ. Given that the other votes are collectively uninformative, the voter follows the most precise signal between the private and the public. Hence, if the private signal is more precise than the public one, following the public signal is strictly dominated.

In what follows, consider the case in which the public signal is more accurate than the private, i.e. $Q > q$. Define by $\mu \in [0, 1]$ the probability that a voter votes according to the public signal when private and public disagree. The next result shows that there exist a unique mixed strategy equilibrium in which voters follow the public signal with positive probability (smaller than one), provided that the precision of the public signal is lower than a threshold, $Q^H$, defined below.

**Proposition 1.** For $Q \in (q, Q^H)$, there exists a unique equilibrium in mixed strategies. In the equilibrium, when the private and public signals agree, the agent always
votes accordingly. When the private and public signals disagree, the agent votes according to the public signal with probability

\[ \mu = \frac{\gamma - q(1 + \gamma)}{1 - q - q\gamma}, \]

where \( \gamma(q, Q, N) = \left( \frac{Q}{1 - Q} \right)^{\frac{1}{1-q}} \frac{q}{1-q}. \)

The threshold \( Q^H \) is given by

\[ Q^H = \frac{1}{1 + \left( \left( -1 + \frac{1}{q} \right)^{\frac{1+q}{1-q}} \right)^{\frac{1+q}{2}}}. \]

Proof. See Appendix for derivation.

Notice that the voting profile described by this equilibrium prescribes to vote according to the public signal with positive probability only if \( Q > q \). The last case to consider is when the public signal precision is above \( Q^H \), and the proof follows from Proposition 1.

**Corollary 1.** Suppose \( Q > Q^H \). Then in equilibrium agents always vote with the public signal.

We can summarize the predictions for the mixed strategy equilibrium as follows:

1. if \( s_i = s_p \), player’s best response is to follow both signals
2. if \( s_i \neq s_p \), then:
   
   (a) if \( Q \leq q \), always follow the private signal \( (\mu = 0) \),
(b) if $Q \in (q, Q^H)$, follow $s_p$ with probability $\mu \in (0, 1)$,

(c) if $Q > Q^H$ always follow the public signal ($\mu = 1$).

While the symmetric responsive equilibrium prescribes to vote according to the public with positive probability, there is another (non-responsive) equilibrium where every voter always conforms to the public signal.

**Proposition 2 (Conformist equilibria).** There exists a Bayesian Nash equilibrium in which every agent votes according to (against) the public signal.

**Proof.** Consider the choice of an individual $i$. If every other agent votes according to (against) the public signal, agent $i$ is not pivotal and therefore she is indifferent about which alternative to vote for. Thus every agent voting according to (against) the public signal is an equilibrium. \qed

Conformist equilibria can be very inefficient, especially when the public signal is less precise than the private signal, or more precise but under the threshold $Q^H$ determined above. That is, introducing a public signal may be deleterious for information aggregation because the public signal might be a focal point which makes coordination easier for committee members.

Besides these two symmetric equilibria, there exist several asymmetric ones where voters conform to the public signal. However, these equilibria do not seem to be very plausible. In particular, as described in the experimental setting below,

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5For instance, consider a committee of five members where each member observes a private signal and everyone observes the same public signal. One equilibrium is that one member of the committee votes with her private signal, when this disagrees with the public, and the other four members vote with (against) the public signal. In another equilibrium, two committee members vote with their private signals, which disagree with the public, and the other three members of the committee vote with (against) the public signal.
groups are randomly matched in each period: because it is difficult to coordinate on asymmetric equilibria with random matching, these asymmetric equilibria are very unlikely to emerge.

**Experimental Design**

The experiment is designed to answer two questions. The first asks to what extent subjects’ behavior responds to signal precision. In particular, the experiment tests whether subjects vote according to the public signal when they know that it is less precise than their private ones. The first treatment of interest changes the relative precision of the private and public signals. I see no evidence of learning in the data, and thus report the results below aggregating over all rounds of the same treatment. The second question asks how salience of public information affects voting behavior. To understand the impact of salience, I create five structurally equivalent games (corresponding to different treatments), in which public information is provided in different ways.

The experiment was organized in ten separate sessions, all held at the Columbia Experimental Laboratory (CELSS). Subjects were registered students, recruited through the laboratory web site. No subject participated in more than one session. Overall, 157 subjects participated in the experiment. The experiment was conducted using the software Z-Tree (Fischbacher, 2007), and a copy of the instructions is presented in the Appendix. Each session lasted about one hour, and earnings ranged from $18 to $28, with an average of $24 (including a $5 show-up fee).

Each session was comprised of 70 rounds. In every round, participants were randomly matched with each other to form a committee of 5 members. Subjects

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6 This is true for the first four sessions. As displayed in Table 1 and explained later, in sessions 5-10 there were no committees and subjects performed an individual task.
were told that their group’s task was to find a prize (worth 70 experimental dollars) which was hidden in one of two boxes, one red, one blue. The computer placed the prize in the red box with probability 50%, and each subject received two pieces of information: a private message and a public message. To make clear that the public message was common knowledge, all public messages were displayed on the two central screens of the laboratory. The private messages were displayed on each subjects’ monitor. After receiving the information, subjects voted for either the red box or the blue box\textsuperscript{7}. The alternative that received the majority of votes was selected. After every round, subjects received feedback about the number of votes cast by their group for the red and blue box, whether the group decision was correct or not, and their earnings for the round. Individual payoffs were based on whether the group decision was correct or incorrect: 70 experimental dollars for each correct decision, 10 experimental dollars for a wrong decision. Subjects were paid the sum of their round earnings.

Table 1 shows which sessions had high public signal accuracy ($Q = 0.7$), and low ($Q = 0.55$). The accuracy of the private signal was set to $q = 0.6$ throughout all sessions. The committee size was set to $n = 5$ for the entire experiment. For these parameters, the equilibrium predictions for the symmetric responsive equilibrium are to follow the public signal 37% of the time when this is more precise than the private ($Q > q$), and never follow it when $Q \leq q$. According to the equilibrium in which subjects coordinate on (against) the public signal, everybody (nobody) follows the public signal when the two signals disagree, even when the public signal is less accurate than the private.

In addition to testing how subject behavior changes with signal relative precision, this experiment studies how salience affects voting decision. Salience is defined along\textsuperscript{7}The position of the vote buttons was randomly shuffled in each round.
two dimensions. The first is recency, or timing relative to voting. I hypothesize that subjects follow more the message that is closer to the vote, because they have the information more readily available in their short-term memory (Crowder, 2014, Cook and Flay, 1978, Nickerson, 2007). The second dimension refers to how information is presented. Information that is visibly stunning is salient, because individuals focus more on items that are striking and perceptible (Tversky and Kahneman, 1974, Bordalo et al., 2012). I describe below the experimental treatments that vary these two dimensions, recency and emphasis. Note that both dimensions can affect the equilibrium predictions only through their possible coordination role.

**Recency.** This treatment varied whether the public signal was displayed before or after the private signal.

**Asymmetric Prior.** The least salient way to convey the public message is not to show it at all. This treatment corresponds to the last 10 rounds of each session. In these rounds, an asymmetric prior was provided instead of a symmetric ($\pi = 0.5$) prior, and no public signal was displayed. Subjects were told that the computer

<table>
<thead>
<tr>
<th>Session</th>
<th>$Q$</th>
<th>Committee, Size</th>
<th># Rounds</th>
<th># Subjects</th>
</tr>
</thead>
<tbody>
<tr>
<td>$s_1$</td>
<td>0.7</td>
<td>Yes, 5</td>
<td>70</td>
<td>20</td>
</tr>
<tr>
<td>$s_2$</td>
<td>0.55</td>
<td>Yes, 5</td>
<td>70</td>
<td>20</td>
</tr>
<tr>
<td>$s_3$</td>
<td>0.7</td>
<td>Yes, 5</td>
<td>70</td>
<td>20</td>
</tr>
<tr>
<td>$s_4$</td>
<td>0.55</td>
<td>Yes, 5</td>
<td>70</td>
<td>15</td>
</tr>
<tr>
<td>$s_5$</td>
<td>0.7</td>
<td>No</td>
<td>70</td>
<td>13</td>
</tr>
<tr>
<td>$s_6$</td>
<td>0.55</td>
<td>No</td>
<td>70</td>
<td>17</td>
</tr>
<tr>
<td>$s_7$</td>
<td>0.7</td>
<td>No</td>
<td>70</td>
<td>10</td>
</tr>
<tr>
<td>$s_8$</td>
<td>0.55</td>
<td>No</td>
<td>70</td>
<td>16</td>
</tr>
<tr>
<td>$s_9$</td>
<td>0.7</td>
<td>No</td>
<td>70</td>
<td>13</td>
</tr>
<tr>
<td>$s_{10}$</td>
<td>0.55</td>
<td>No</td>
<td>70</td>
<td>13</td>
</tr>
</tbody>
</table>

Table 1: Summary of experimental sessions. The accuracy of the private signal was set to $q = 0.6$ throughout the whole experiment. A total of 75 subjects were assigned to a “group” condition, and divided in committees of size five. The other 82 subjects were assigned to an “individual” condition.
placed the prize in the blue box with probability $\pi = 0.7$ (or $\pi = 0.55$, depending on the session), and in each round each subject received only a private signal. From a Bayesian standpoint, these ten rounds conveyed the same information as the previous ones: having a symmetric prior and a public signal with accuracy $Q = 0.7$ is identical to having an asymmetric prior $\pi = 0.7$ and no public signal. After receiving the private message, subjects were asked to vote for one of the two boxes, as in the first part of the experiment.

**Jingle.** This treatment varied the way the public signal was projected on the central screens. In the absence of this treatment, the public signal was displayed with the picture of a blue or red box (as for the private signals projected on subjects’ monitors). With the jingle treatment, the public message was projected on the central screen with a video displaying a star jumping within an empty, white box, which then became either red or blue. The video was accompanied by a striking soundtrack, and to make the jingle treatment less repetitive, the music theme varied. I used famous music pieces such as Also sprach Zarathustra by Strauss, Eye of the tiger, The final Countdown, Thrift Shop and the Game of Thrones’ soundtrack. I hypothesize that salience of the public signal is increasing in both recency and emphasis.

Subjects in different sessions were presented with the same five treatments. Each subject played thirty rounds with the public signal displayed before the private, and thirty with the private displayed before the public. Among each of these thirty rounds, eight displayed the public message with the jingle, so that it is possible to evaluate the interaction between jingle and recency treatments. I decided to keep

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8 All the videos can be accessed at the following link: https://www.dropbox.com/sh/40lkfpczvd0b8x/AACayVLFoSEJ2Zam3leXFt3da?dl=0
9 Administering the salience treatments within subjects was a natural choice to get more data points under the time and budget constraints.
the number of jingle rounds small to ensure novelty and subjects’ interest. These conditions (recency, jingle) were randomly selected in every round, a feature designed to keep subjects engaged in the task. The only condition that was not randomly assigned is the asymmetric prior treatment, which consisted in the last ten rounds that every subject played. This design feature was chosen in order to avoid subjects from learning the correct posterior from the researcher.\textsuperscript{10} Table 2 shows the number of rounds for each of the treatments.

<table>
<thead>
<tr>
<th></th>
<th>Jingle</th>
<th>NoJingle</th>
</tr>
</thead>
<tbody>
<tr>
<td>Asymmetric prior</td>
<td>-</td>
<td>10 rounds</td>
</tr>
<tr>
<td>Public first</td>
<td>8 rounds</td>
<td>22 rounds</td>
</tr>
<tr>
<td>Private first</td>
<td>8 rounds</td>
<td>22 rounds</td>
</tr>
</tbody>
</table>

Table 2: Factorial design for every session (for both $Q > q$ and $Q \leq q$). The row values are associated to the recency treatment (i.e. whether the private signal was displayed before or after the public). The column values are associated with the jingle treatment. The values within the matrix display the number of rounds for each interaction.

Results

The first treatment of interest is designed to test whether subjects in committees follow more the public signal when it is more accurate than the private. I begin by aggregating the data across the salience treatments, given that salience is irrelevant according to the theory. Figure 1 displays the fraction of votes cast according to the public signal when the private and public signals disagree (estimated $\mu$), as well as when the two signals agree. The second panel gives us a measure of the extent of pure noise in the experiment.

The first thing to notice is that the treatment effect goes in the expected direction: subjects vote more with the public signal when this is more precise than

\textsuperscript{10}In this case, the public signal is not displayed, and the task is easier because subjects do not need to update the public signal: the update is done by the researcher and told during the instructions in the form of asymmetric prior.
Figure 1: **Responsiveness of vote to signals' precision**: Average fraction of votes with public signal in sessions with committee decisions, and associated 95% confidence intervals. Standard errors are clustered at the individual level. In the left plot, the public signal and the private signal disagree, and red lines represent the symmetric responsive equilibrium prediction for \( \mu \), the probability of voting with the public signal under mismatch. In the right plot, the signals agree, and blue lines represent the unique optimal decision when the two signals agree.

the private one (21% vs 66%, statistically significant at any conventional level). However, the observed behavior is far from the symmetric responsive equilibrium predictions (red line in Figure 1), as well as from the conformist equilibria. In particular, it is worth noting that 21% of the subjects vote according to the public signal even when this is less precise than the private one, when the two disagree (left column, left plot). When presented with the trivial choice of voting after receiving two identical signals, subjects tend to vote according to both. Nevertheless, even
in this case subjects commit mistakes, quantified in the right plot by the distance between the bars and the blue lines (less than 10%).

**Result 1** Subjects tend to follow the public signal more than predicted by the symmetric responsive equilibrium.

Given this result, the mechanism according to which voters follow public signals because of their informativeness lacks explanatory power. It follows that subjects might be influenced by public information because of conformity, or because of bias in information processing. We know there exist two symmetric conformist equilibria with coordination on (or against) the public signal, and several asymmetric equilibria. However, all of these equilibria are not responsive to the relative precision of the two signals. Since we clearly see that the behavior of voters responds to signals’ relative precision (treatment effect in Figure 1), all the non-responsive equilibria do not reflect subjects’ behavior.

The results in Figure 1 can be disaggregated to shed light on individual behavior. Figure 2 plots the proportion of times each subject votes according to the public signal. We know that in equilibrium this proportion should be 37% when $Q > q$ and zero when $Q \leq q$ (when the public and private signals disagree). On the other hand, were people playing the conformist equilibrium, the proportion would be close to one for both values of signal precision. Figure 2 show these equilibrium predictions and subjects’ “mistakes”, which are bigger as the distance between the

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11It could be that subjects realize that others do not play the symmetric responsive equilibrium, and best respond to that. If this was the case, subject would best respond by voting with the public less than what prescribed by the symmetric responsive equilibrium. By looking at the average vote with the public at each session level and computing the best reply to this average, it is clear that in each session subjects followed the public signal more than what these best replies to experimental data predict.

12It might be that some subjects are playing the conformist equilibria and others are mixing. With Figure 1 we would not be able to disentagle between the two behaviors.
Figure 2: **Individual “mistakes” under mismatch**: Red lines represent the symmetric equilibrium predictions for $\mu$, when the public and private signal disagree. Blue lines represent the conformist equilibrium prediction. When $Q > q$ (upper picture), the number of subjects who vote more with the public signal is greater than when $Q < q$ (lower picture).

Equilibrium predictions and the bars increase. This result again contradicts the coordination motive of players, as more subjects vote following the public signal when its precision is higher (upper graph) than when it is lower than the private one (lower graph).

One concern that could arise is that subjects’ behavior changed over time, approaching the theoretical predictions of the equilibria analyzed. Figure 17 in Appendix analyzes the dynamics of subjects’ behavior over time, showing that there is no convergence to equilibrium predictions as the final rounds approach.
The next section describes how subjects responded to salience of public signals. According to the salience mechanism, framing leads subjects to select a strategy based on the frame itself, even if it is strategically irrelevant.

Subjects’ response to salience

This section reports separately the results for each salience treatment, starting from the asymmetric prior, which is the treatment where the public message is least salient (as it is not displayed at all), and continuing with the more salient treatments (recency and jingle).

Asymmetric Prior. Figure 3 shows the proportion of votes with the public signal (under mismatch) in the treatment with public signal calculated by aggregating over the other salience treatments vs the treatment with asymmetric prior. The left bars correspond to the public signal being less accurate than the private \((Q < q)\), and we see no difference. When \(Q > q\) instead, subjects follow the public signal more (as we saw earlier), and the treatment effect of showing the public signal is high and significant: showing the public signal correlates with subjects voting for it 14% of the times more than when the same signal is conflated in the prior. This difference is significant at the ten percent level. This treatment effect has the same direction of what found in Kawamura and Vlaseros (2017),\(^{13}\) although the magnitude is much smaller. One concern might be that any effect of the asymmetric prior treatment is driven by it being administered during the last ten rounds of each session. I performed the same comparison as in figure 3 considering only the last ten rounds of the first part of the experiment, when the public signal was displayed. Even with

\(^{13}\)Kawamura and Vlaseros (2017) only analyze the case where \(Q > q\), with slightly different parameters and committee size.
this reduced sample, there is no difference when the public signal is less precise. When the public signal is more precise, this difference is reduced to 11 percentage points, significant at the ten percent level.

Figure 3: **Asymmetric prior treatment**: Average fraction of votes with public signal under mismatch, and 95% confidence intervals. Standard errors are clustered at the individual level. Red column correspond to rounds where the public signal was provided. The blue columns correspond to the last 10 rounds in each sessions, where the public signal content was conflated in the prior. Note: Red lines represent the symmetric responsive equilibrium prediction for $\mu$.

**Recency.** The recency treatment varied whether the public signal was projected on the central screens of the laboratory before or after the private signals were displayed on the subjects’ monitors. Recency effects were substantively and statistically sig-
nificant. In particular, when the public signal accuracy is higher (right columns in Figure 4), there is a 16% difference between the fraction of times subjects followed the public signal when it was displayed before the private (60%) as opposed to closer to the vote (76%). When the public signal accuracy is lower than the private (left columns), there is a 11% difference. Both differences are significant at any conventional level.

Figure 4: **Recency effect**: Average fraction of votes with public signal under mismatch, and 95% confidence intervals. Standard errors are clustered at the individual level. Red columns correspond to rounds where the public signal is displayed first. Red lines represent symmetric responsive equilibrium predictions for $\mu$.

**Result 2** *Subjects follow the public signal more when it is displayed last, before the*
voting decision.

Jingle. For what concerns the jingle treatment effect, the direction is the one expected and it is in line with the recency treatment effect. The magnitude is smaller, as Figure 5 shows. When the public signal accuracy is higher (right columns in Figure 5), there is a 4% difference between the fraction of times subjects followed the public signal when it was displayed before the private (67%) as opposed to closer to the vote (71%). When the public signal accuracy is lower than the private (left columns), there is a 5% difference.

Table 3 shows an OLS regression of the probability of following the public signal under mismatch, regressed on the jingle treatment and the recency treatment. When the public signal is presented as a flashy video, subjects vote for it 4.7% of the time more. When we interact the jingle with recency, the effect increases to 5.9%. Even though the aggregate effect of the jingle is not significant, there is a pattern of response to it: subjects react more to the initial jingles. In particular, if the jingles are shown within the first 15 periods, subjects follow the public signal more than public signal displayed in later periods (12% difference, \( p < 0.01 \)).

Given the magnitude and significance of the recency treatment effect, the question that arises is whether this effect is homogeneous across subjects. Figure 6 shows the individual treatment effect of recency of the public signal. Each dot represents the proportion of times each subject voted with the public signal. The vertical distance between red and blue dots is the individual average treatment effect of providing a public signal before vs after the private one. The left panel corresponds to a more precise public signal. Recency of the public signal has a striking homogeneous, positive effect on the proportion of time each individual votes with the public sig-
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<td></td>
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Table 3: OLS regression. The dependent variable is a dummy variable equal to 1 when public and private signals differ, and the subject votes according to the public signal, 0 otherwise. The variable *Jingle* is a dummy variable equal to 1 when the public information is displayed with a salient video, and the variable *Public last* is a dummy variable equal to 1 when the public signal is displayed after the private signal. Column (3) shows that, when controlling for order effects, the effect of the jingle remains significant, but the magnitude of recency is higher. Standard errors are clustered at the individual level in parenthesis. * corresponds to $p < 0.1$, ** to $p < 0.05$, and *** to $p < 0.01$. 

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Figure 5: **Jingle effect**: Average fraction of votes with public signal under mismatch, and 95% confidence intervals. Standard errors are clustered at the individual level. Red columns correspond to rounds where the public signal is displayed with the jingle. Red lines represent symmetric responsive equilibrium predictions for $\mu$.

We can see this effect from the proportion of times each individual voted with the public signal when it is displayed closer to the vote (red dots), which is always above the same proportion when the public signal is displayed before the private signal (blue dots): the “Public Last” (recency) treatment first order stochastically dominates the “Public First” treatment.\(^{14}\)

Overall, there is a substantial fraction of subjects who always vote according to

\(^{14}\)I also performed a Kolmogorov–Smirnov test to compare the two samples of voting with the public signal when it is provided before or after the private. Although we cannot reject that the two distribution are the same (with a p-value of 0.15), the number of observation is too small to rely on this result, and graphically showing the ECDFs provides much better evidence.
the most recent signal. In particular, votes match the most recent signal in 74% of individual decision, which is a remarkable result given that from a theoretical standpoint behavior should not be affected by the time a message is released. Moreover, subjects’ behavior is homogeneous across different sessions.\footnote{As Figures 12 and 13 in appendix show, there are no session-specific effects: individual votes are homogeneous across different sessions.}

**Individual Treatment Sessions**

In the previous section, I show that the way subjects responded to the signals’ relative precision rules out the coordination mechanism, which is a possibility that might arise (see conformity equilibrium in the theory section). Sessions 5-10 were
designed to fully control for this coordination mechanism. The structure of these sessions was identical to the previous four, except that subjects were paid for their individual decisions, and were not part of any group. Instructions were given to subjects in the same way as in the first sessions, with the only difference that no groups were mentioned. The absence of groups made the decision much easier, being absent any calculus of pivotality or coordination problem. The decision problem was straightforward, as it only required to compare the relative precision of the signals received: the expected payoff maximizing decision was to always follow the information contained in the more accurate message.

If less subjects followed the public signal in these individual sessions, we would have evidence that subjects used the public signal as a coordination device: voters would conform to the public signal’s content as long as they were in groups, but would stop to conform when the task was individual. If, on the other hand, the fractions of people voting with the public signal were similar in the individual and group treatments, it would be evidence that subjects did not use the public signal as a coordination device.

Aggregate data for these individual sessions show that there is no substantive difference between the fraction of votes cast according to the public signal in the individual task treatment vs. the treatment with committees and group decisions (see Figure 7).

The aggregate data show that, when the public signal is less precise than the private, subjects tend to over-follow the public (the optimal decision is to never vote with the public in both group and individual treatments). The treatment effect of relative signal precision remains in the correct direction even in the individual sessions. The similar results that we observe in the group task and individual task sessions provide evidence against the strategic explanation for the group treatment.
Yet, the fact that individuals vote too little with the public signal when it is more informative than the private is surprising, given the very simple task they are given. This result might be due to the way subjects were exposed to the messages during the experiment. Although preserving the same experimental design used in the first sessions with the group task was the most linear way to compare the two treatment conditions, some subjects might have been confused by receiving a public signal common to everyone in the room, when their payoff was determined uniquely by their decision. Hence, despite very clear instructions, the individual task might have confused some subjects.
Yet, as Figure 8 shows, individual data for the individual sessions show the same stochastic dominance that we saw in group sessions for the recency treatment. Even for these subjects, recency of the public signal has a homogeneous and positive effect on the proportion of time each individual votes with the public signal. We can see this effect from the distribution of individual votes when the public signal is displayed closer to the vote (red dots), which stochastically dominates the votes when the public signal is displayed before the private (blue dots). Even the jingle has an effect that is similar to the group sessions: when the public signal is presented as a flashy video with salient music, the probability that subjects vote for it is 5% higher (p-value lower than 10%), although when interacted with recency, this effect is not significant anymore (table 4 in appendix shows the OLS regression coefficients for the individual sessions). Overall, the individual sessions show that salience treatment effects (particularly in the form of recency) are robust to the nature of the task: whether subjects vote in groups or individually, they are clearly affected by the way the message is presented.\textsuperscript{16}

Conclusion

This paper studies the effect of salient public signals on voting behavior in a majoritarian voting game with common interest. The model shows that in the presence of public signals there exist two main equilibria of interest: a symmetric responsive equilibrium, where subjects follow their private signals with positive probability, and a Bayesian equilibrium where subjects coordinate on the information provided by the public signal. Theoretically, subjects’ behavior should not be affected by signals’ salience, as long as the informational content of the signals is the same.\textsuperscript{16}

\textsuperscript{16}All the salience treatment effects in the individual task sessions are shown in the Appendix.
A laboratory experiment tests the model, suggesting several conclusions. First, subjects tend to follow the public signal more than what is predicted by the symmetric responsive equilibrium. If subjects treated public signals as information devices, we would expect this result only for the treatment with high public signal accuracy \((Q > q)\), as in Kawamura and Vlaseros (2017). Yet, subjects tend to over follow the public signal even when it is less accurate than the private one, as Figure 1 shows. One might hypothesize that public signals are focal points acting as coordination devices when decisions are taken in groups. As shown in Figure 2, this mechanism is contradicted by the data. Moreover, results from the individual sessions disregard the coordination mechanism, as subjects vote very similarly whether they are in groups or not.
The second conclusion is that salience of information affects voter behavior. Different treatments investigate whether subjects follow the public signal because it is displayed in a salient manner. In particular, experimental results show that the order of message delivery matters, as subjects tend to follow the public signal more when it is the most recent signal observed before voting. Interestingly, this finding is robust to sessions where subjects do not vote in committees over issues of common interest. This result of recency effect mirrors what observed in field experiments on political message effectiveness during electoral campaigns (Nickerson, 2007).

The effect of recency of public information can have important political implications. Consider for instance the timing of political scandals’ breaking: if the timing of message delivery matters, then it is more likely that voters take into account a scandal involving a politician when voting if the scandal happens close to the election date. A recent illustration of what is known as an “October surprise” in American Politics was Comey’s announcement about reopening the email investigation of Hillary Clinton’s emails. The announcement came on October 28, 2016, ten days before the Presidential election won by Donald Trump. Although it is hard to assess the effect of this announcement on the election’s outcome, it is reasonable to believe that this affected voters more than had it been announced six months before. The fact that voters overreact to salient, recent information, can explain the strategic choice of when to drop a bombshell.

References


Online Appendix

Proofs

Let’s first consider for simplicity a committee of size \(n = 3\). The next section generalizes to committees of arbitrary size. Define by \(\mu\) the probability that a voter votes according to her public signal (in favor of state \(A\)), when the private signal is the opposite (in favor of state \(B\)), i.e. \(\mu = Pr(v_i = \alpha | s_i = \beta, s_p = \alpha)\).

Lemma 1: Informative Voting

First, we want to look for an equilibrium where agents never follow the public signal, when the private signal goes in the opposite direction. Under pivotality, the posterior probabilities of state \(A\) and state \(B\) being true given signals \(s_i = \alpha, s_p = \beta\) are respectively

\[
Pr[A|s_i = \alpha, s_p = \beta, piv] = \frac{Pr[s_i = \alpha | A]Pr[s_p = \beta | A]Pr[piv | A, s_i = \alpha, s_p = \beta]Pr(A)}{Pr[s_i = \alpha, s_p = \beta, piv | A] + Pr[s_i = \alpha, s_p = \beta, piv | B]} = \frac{q(1 - Q)q(1 - \mu)[q\mu + (1 - q)1]\pi}{q(1 - Q)q(1 - \mu)[q\mu + (1 - q)1] + (1 - q)Q(1 - q)(1 - \mu)[q1 + (1 - q)\mu]}
\]

and

\[
Pr[B|s_i = \alpha, s_p = \beta, piv] = \frac{Pr[s_i = \alpha | B]Pr[s_p = \beta | B]Pr[piv | B, s_i = \alpha, s_p = \beta]Pr(B)}{Pr[s_i = \alpha, s_p = \beta, piv | A] + Pr[s_i = \alpha, s_p = \beta, piv | B]} = \frac{(1 - q)Q[(1 - q)(1 - \mu)][q1 + (1 - q)\mu]\pi}{q(1 - Q)q(1 - \mu)[q\mu + (1 - q)1] + (1 - q)Q(1 - q)(1 - \mu)[q1 + (1 - q)\mu]}
\]
Player $i$ votes for alternative $A$ when receiving signals $s_i = \alpha$ and $s_p = \beta$ if

$$EU(v_i = A|s_i = \alpha, s_p = \beta, S_{-i}) \geq EU(v_i = B|s_i = \alpha, s_p = \beta, S_{-i})$$

With a normalized utility function, under pivotality:

$$EU(v_i = A|\alpha, \beta, piv) = \frac{q(1 - Q)q(1 - \mu)[q \mu + (1 - q)1]|\pi}{q(1 - Q)q(1 - \mu)[q \mu + (1 - q)1] + (1 - q)Q(1 - q)(1 - \mu)[q1 + (1 - q)\mu]}$$

$$EU(v_i = B|\alpha, \beta, piv) = \frac{(1 - q)Q[(1 - q)(1 - \mu)][q1 + (1 - q)\mu]|\pi}{q(1 - Q)q(1 - \mu)[q \mu + (1 - q)1] + (1 - q)Q(1 - q)(1 - \mu)[q1 + (1 - q)\mu]}$$

We are looking for an equilibrium in which agents always follow the private signal, when the public signal goes in the opposite direction: this corresponds to $\mu = 0$. For this value of $\mu$, the pure strategy is to vote according to the private signal whenever its accuracy is greater than that of the public one. To find corresponding values on the signals’ precision, it suffices to set from the previous expressions the expected utilities for the two alternatives equal

$$EU(v_i = A|s_i = 0, s_p = 1, pivot) = EU(v_i = B|s_i = 0, s_p = 1, pivot)$$

$$q(1 - Q) = (1 - q)Q$$

to find the value $Q = q$. Hence, there exists an equilibrium in which every agent always vote with the private signal if and only if $Q \leq q$. In this equilibrium, agents never follow the public signal, i.e. $\mu = 0$. 

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Proposition 1: Symmetric Responsive Equilibrium

Committee of size 3. In order to characterize the equilibrium mixing probability, \(\mu\), we set equal the expected utilities for the two alternatives

\[
EU(v_i = A | s_i = \alpha, s_p = \beta, piv) = EU(v_i = B | s_i = \alpha, s_p = \beta, piv) \\
q^2(1 - Q)[1 - q(1 - \mu)] = (1 - q)^2Q[1 - (1 - \mu)(1 - q)], \\
q^2(1 - Q) - \mu q^3(1 - Q) = (1 - q)^2Q - \mu(1 - q)^3Q \\
\mu[(1 - q)^3Q - q^3(1 - Q)] = (1 - q)^2Q - q^2(1 - Q)
\]

which corresponds to the following value for the equilibrium probability of following the public signal

\[
\mu = \frac{(q - 1)q(q - Q)}{q^3 - 3(q - 1)qQ - q}
\]

In order to find the threshold \(Q_H\), consider the case of \(\mu = 1\). For this value of \(\mu\), the pure strategy is to vote according to the public signal whenever its accuracy is greater than the following value. In a committee of three members, this is equal to

\[
EU(v_i = A | s_i = 0, s_p = 1, piv) = EU(v_i = B | s_i = 0, s_p = 1, piv) \\
q(1 - Q) - (1 - q)Q = 0 \\
\frac{1}{Q} - 1 = \frac{(1 - 2q + q^2)}{q^2} \\
\frac{1}{Q} = \frac{(1 - 2q + q^2 + q^2)}{q^2} \\
Q_H = \frac{q^2}{(1 - 2q + 2q^2)}.
\]
Committee of arbitrary size. Consider a committee of arbitrary size \( N \) (with \( N \) odd). In order to characterize the equilibrium mixing probability, \( \mu \), set

\[
EU(v_i = A | s_i = \alpha, s_p = \beta, \text{pivot}) = EU(v_i = B | s_i = \alpha, s_p = \beta, \text{pivot})
\]

\[
\pi q (1 - Q) \left( \frac{N - 1}{N - 1} \right)^{\frac{N - 1}{2}} [1 - \mu q]^{\frac{N - 1}{2}} = \pi Q (1 - q) \left( \frac{N - 1}{N - 1} \right)^{\frac{N - 1}{2}} [1 - \mu (1 - q)]^{\frac{N - 1}{2}}
\]

\[
q (1 - Q) \left( \frac{N - 1}{N - 1} \right)^{\frac{N - 1}{2}} [1 - \mu q]^{\frac{N - 1}{2}} = Q (1 - q) \left( \frac{N - 1}{N - 1} \right)^{\frac{N - 1}{2}} [(1 - \mu) (1 - q)]^{\frac{N - 1}{2}}
\]

Rearranging we get the following:

\[
\frac{q}{(1 - q)} \left( \frac{q/1 - q}{Q/1 - Q} \right)^{\frac{2}{N - 1}} \mu [1 - q + q (1 - \mu)] = [q = (1 - q)(1 - \mu)]
\]

We want to solve for \( \mu \): one obvious solution of the previous equation is to set \( \mu \) equal to zero. For the non-trivial solution, let’s call \( \gamma \) the following value

\[
\gamma \left[ 1 - (1 - \mu) q \right] = 1 - (1 - q)(1 - \mu)
\]

Solving for \( \mu \), we get

\[
\mu = \frac{\gamma - q (1 + \gamma)}{1 - q - q \gamma},
\]

Therefore, in a committee of arbitrary size, the agents whose private signal disagrees with the public vote according to the private with probability \( \mu = \frac{\gamma - q (1 + \gamma)}{1 - q - q \gamma} \), where

\[
\gamma (q, Q, N) = \left( \frac{q/1 - q}{Q/1 - Q} \right)^{\frac{2}{N - 1}} \frac{q}{(1 - q)}. A \text{ proof of uniqueness is provided by Wit (1998) and Kawamura and Vlaseros (2017).}
\]
Figure 9: Asymmetric prior treatment in individual sessions. Average fraction of votes with public signal under mismatch and 95% confidence intervals. Standard errors are clustered at the individual level. The blue columns correspond to the last 10 rounds in each sessions, where the public signal content was conflated in the prior. Note: Blue lines represent the unique optimal decision in the individual treatment (follow the more precise signal).
Figure 10: Recency effects in individual sessions. Average fraction of votes with public signal under mismatch and 95% confidence intervals. Standard errors are clustered at the individual level. Blue lines represent the unique optimal decision in the individual treatment (follow the more precise signal).
Figure 11: Jingle effects in individual sessions. Average fraction of votes with public signal under mismatch and 95% confidence intervals. Standard errors are clustered at the individual level. Blue lines represent the unique optimal decision in the individual treatment (follow the more precise signal).
Table 4: Jingle and recency effects in individual sessions. The dependent variable is a dummy variable equal to 1 when public and private signals differ, and the subject votes according to the public signal, 0 otherwise. The variable *Jingle* is a dummy variable equal to 1 when the public information is displayed with a salient video, and the variable *Public last* is a dummy variable equal to 1 when the public signal is displayed before the private signal. Column (3) shows that when controlling for order effects, the effect of the jingle is not significant anymore. Standard errors are clustered at the individual level in parenthesis. * corresponds to $p < 0.1$, ** to $p < 0.05$, and *** to $p < 0.01$.

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Individual Data

For the individual analysis, I first consider subjects in session 1 through 4, those with committees and a group decision making problem. Figure 12 clearly shows that subjects are homogeneous across different sessions. The plots indicate the proportion of times that each individual voted according to the private signal. The left image is for the sessions with higher public signal accuracy \( Q > q \), and the right one for the others \( q < Q \). Figure 13 performs the same check for the sessions with an individual task. There is no evidence that subjects respond heterogeneously to the public accuracy treatment.

![Individual Subject Votes with Public Signal, Given Mismatched Signals](image)

Figure 12: Proportion of times each individual voted according to the public signal in the first four sessions (with group task). The left image plots values for sessions where \( Q > q \), the right one \( Q < q \). Different colors correspond to different sessions.

Recall that each session is comprised of 70 rounds, and in the last ten rounds subjects received an asymmetric prior and no public signal. The information conveyed was the same. Figure 14 plots, for the group treatment, the difference in how individuals
vote when they receive two separate signals, a private and a public (first 60 sessions), and when they only receive a private, and the public information is conveyed by the prior (last ten rounds). This treatment tests the null hypothesis that individuals behave as Bayesian in recognizing that the posterior is the same in the two cases. As we can see there is a lot of heterogeneity, which leads us to reject the null hypothesis of constant treatment effect among our subjects. The same robustness check is run for the recency and jingle treatments, and is displayed in the figures that follow.

Figure 13: Proportion of times each individual voted according to the public signal in sessions 5-10 (with individual task). The left image plots values for sessions where \( Q > q \), the right one \( Q < q \). Different colors correspond to different sessions.
Figure 14: Asymmetric Prior (group task): Proportion of times each individual voted according to the public signal. The left image plots values for sessions where $Q > q$, the right one $Q < q$. Red dots correspond to the public signal delivered, blue dots to public signal conflated in the prior.
Figure 15: Jingle effect (group sessions). Proportion of times each individual voted according to the public signal. The left image plots values for sessions where $Q > q$, the right one $Q < q$. Blue dots correspond to the public signal displayed with the jingle.
Figure 16: Jingle effect (individual sessions). Proportion of times each individual voted according to the public signal. The left image plots values for sessions where $Q > q$, the right one $Q < q$. Blue dots correspond to the public signal displayed with the jingle.

Figure 17: No Learning. This figure plots aggregate votes as a function of time (experimental rounds. Subjects’ behavior does not approach theoretical predictions.)
Experimental Instructions

Welcome to the Lab! Please, listen to these instructions carefully. If you have any question at any point, please raise your hand. Communication between participants is not allowed during the experiment.

Your participation to the experiment will be rewarded by a payment in cash, immediately and privately after the experiment. The amount of money that you will earn depends on your decisions, the decisions of other participants, and on luck. During the experiment, your earnings will be calculated in experimental currency. After the experiment, your payoff will be converted into dollars (USD) according to the following conversion rate: 200 experimental dollars = 1 US dollar, rounded to the closest integer value. Additionally, you will receive 5 US dollars as a show-up fee, independently of the results during the experiment.

The experiment is comprised of two parts. The first part consists of a total of 60 rounds. The second part consists of a total of 10 rounds. During the first part, in every round you will be randomly divided in groups of five people. All participants are anonymous; nobody knows which other participants are in their group, and nobody will be told who was in which group after the experiment. Each group will make the same decisions, but what happens in the other groups has no relevance for yours. At the end of each round, the groups are newly shuffled.

At the beginning of each round, the computer places a prize in one of two virtual boxes: the blue box or the red box. It is equally likely that the prize is placed in either box. You will not know which box the computer has chosen. Each group’s task will be to guess which box contains the prize.

Each participant will receive two separate messages about the location of the prize. These are the instructions for sessions with group task and high public signal accuracy. The other instructions and the pictures displayed during the instruction period are available upon request.
prize. One message is private and only you can see it. The other message is public and everyone sees it.

The private message you receive is more likely to be correct than not, but it’s not perfectly reliable. It is correct on average 60% of the times. The message is generated by the computer independently for each group member and revealed to each member separately. Private messages can be different for different group members.

In addition to the private message everyone receives, a public message will appear on the central screens. Is it correct on average 60% of the time. The public message may appear in different ways but its accuracy does not depend on the format it takes [emphasize].

Neither the public message nor the private messages are 100% reliable in predicting which box contains the prize, but both messages are more likely to be correct than incorrect. Consider the table on the screen: If the box selected by the computer is the red one, it is more likely that both messages are correct than not, and the least likely event is that both are wrong. [Picture 2].

After you and every member of your group have received both messages, you will be asked to guess which box contains the prize. You have two options: you can either vote for BLUE or for RED [SHOW PICTURE 3].

Remember that what matters for your earnings is the group decision. The box that receives the majority of the votes in your group of 5 people is the group choice for the round. In every round, each member of the group earns:

- 70 experimental dollars if the group guessed the correct box;
- 10 experimental dollars if the group guessed the wrong box.

Your earnings are determined exclusively by the group choice. These earnings
are independent of how a particular group member voted.

At the end of the round you will learn:

1. The number of votes for the blue box cast by your group;
2. The number of votes for the red box cast by your group;
3. The box selected by majority in your group;
4. The outcome of the period: that is, whether the group decision was correct or not;
5. The earnings for the round.

This feedback screen marks the end of the round. After everyone votes, you will move to the next round, in which new groups are formed randomly. The prize is again randomly placed in one of the two boxes, and each box is equally likely to be selected.

In order to begin the experiment, you need to correctly answer to a brief questionnaire. If you have any question, ask now or during the questionnaire. When all the participants have completed the questionnaire, the first round of the experiment will automatically start.

**Last Ten Rounds**

Now that the first part of the experiment ended, you will start the second part, which is comprised of ten rounds.

As in part 1, at the beginning of each round, the computer places a prize in one of two virtual boxes: the blue box or the red box. Differently from the first part,
in these rounds the computer places the prize in the BLUE box 7 out of 10 times, which means 70%. [slide: THE PRIZE IS PLACED IN BLUE BOX 7 OUT OF 10 TIMES]. The box that does not contain the prize remains empty. You will not know which box the computer has chosen. As in the previous part, the group’s task will be to guess which box contains the prize.

In this part of the experiment, you will receive only a private message about the location of the prize. The private message you receive is more likely to be correct than not, but it’s not perfectly reliable. It is correct on average 6 out of 10 times, which means 60%. The message is generated by the computer independently for each group member and revealed to each member separately. Private messages can be different for different group members. No other participant of the experiment will know which private message you received.

After you and every member of your group have received a message, you will be asked to guess which box contains the prize. As in part 1, you will see a feedback screen at the end of each round. If there are no question, you can now begin part 2.

We have now completed the experiment. Please, remain seated and wait for your number to be called and receive your payment.